

Roll No.

MAT–510

Mathematical Programming

M. Sc. MATHEMATICS (MSCMAT–12)

Second Year, Examination, 2017

Time : 3 Hours

Max. Marks : 60

Note : This paper is of **sixty (60)** marks containing **three (03)** sections A, B and C. Attempt the questions contained in these sections according to the detailed instructions given therein.

Section–A

(Long Answer Type Questions)

Note : Section ‘A’ contains four (04) long answer type questions of fifteen (15) marks each. Learners are required to answer *two* (02) questions only.

1. Solve the following non-linear programming problem using the method of Lagrangian multipliers :

Max. :

$$z = 6x_1 + 8x_2 - x_1^2 - x_2^2$$

Subject to :

$$4x_1 + 3x_2 = 16$$

$$3x_1 + 5x_2 = 5$$

and $x_1, x_2 \geq 0$.

2. By deriving the necessary Kuhn-Tucker conditions and using Wolf's method, solve the following quadratic programming problem.

Max. :

$$z = 2x_1 + x_2 - x_1^2$$

Subject to :

$$2x_1 + 3x_2 \leq 6$$

$$2x_1 + x_2 \leq 4$$

and $x_1, x_2 \geq 0$.

3. Define Duality. Derive the dual of the quadratic program :

Min. :

$$\left(C^T x + \frac{1}{2} x^T C x \right)$$

Subject to :

$$Ax \geq b$$

where A is $m \times n$ real matrix and G is $m \times n$ symmetric matrix.

4. Use the revised Simplex method to solve the linear programming problem :

Min. :

$$z = -2x_1 - x_2$$

S. t. :

$$x_1 + x_2 \geq 2$$

$$x_1 + x_2 \leq 4$$

and $x_1, x_2 \geq 0$.

Section-B**(Short Answer Type Questions)**

Note : Section 'B' contains eight (08) short answer type questions of five (5) marks each. Learners are required to answer *four* (04) questions only.

1. State the features of Dynamic programming problem.
2. Define convexity. Check whether the following function is a convex function or not :

$$f(x, y) = x^2 - 3xy + y^2$$

3. Solve the integer programming problem by branch and bound method :

Max. :

$$z = 7x_1 + 9x_2$$

Subject to :

$$-x_1 + 3x_2 \leq 6$$

$$7x_1 + x_2 \leq 35$$

and $0 \leq x_1, x_2 \leq 7$.

4. What are separable programming function ? Explain with suitable example.
5. Solve by Kuhn-Tucker condition :

Max. :

$$z = 10x_1 + 4x_2 - 2x_1^2 - x_2^2$$

Subject to :

$$2x_1 + x_2 \leq 5$$

and $x_1, x_2 \geq 0$.

6. Let $S \subset \mathbb{R}^n$ be a convex set, H a supporting hyperplane of S and $T = S \cap H$, prove that every extreme point of T is an extreme point of S .
7. Write the algorithm for the solution of a integer programming problem by Gomory method.
8. Use dynamic programming to solve the linear programming problem :

Max. :

$$z = x_1 + 9x_2$$

S. t. :

$$2x_1 + x_2 \leq 25$$

$$x_2 \leq 11$$

and $x_1, x_2 \geq 0$.

Section-C

(Objective Type Questions)

Note : Section 'C' contains ten (10) objective type questions of one (01) mark each. All the questions of this section are compulsory.

1. (A) Write True/False in the following questions :
 - (i) Every local minimum of the convex program is a global minimum.
 - (ii) Branch and bound methods are used to solved both pure and mixed integer linear programming problem.
 - (iii) The optimum solution of a non-linear programming problem is at an extreme point of the feasible region.

- (iv) The Hessian matrix used for solving non-linear programming problem is defined as the square matrix of second order partial derivatives.
 - (v) In quadratic programming, only the objective function is non-linear while all the constraints are linear functions.
- (B) Fill in the blanks in the following questions :
- (i) A function $f(x_1, x_2, \dots, x_n)$ is said to be separable if

$$f(x_1, x_2, \dots, x_n) = \dots\dots\dots$$
 - (ii) is used for getting the stationary points of the constrained non-linear programming problem.
 - (iii) Dynamic programming is a Mathematical technique dealing with the optimization of
 - (iv) In convex set, the line joining two points x_1 and x_2 in the set form is written as
 - (v) The Lagrangian multipliers of the programming problem :

$$\text{Min } (-x^2)$$

$$\text{Subject to } 0 \leq x \leq 1$$

is

